

Lecture 1 – Combinatorial Testing

AAA705: Software Testing and Quality Assurance

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2024 Spring



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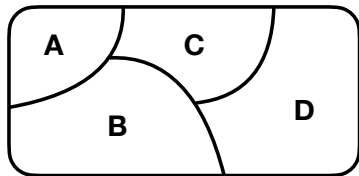
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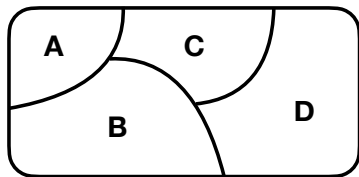
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- In general, **exhaustive testing** is not feasible. It means that we **cannot guarantee** that the software is free of defects.
- We need to pick a good set of test cases to **maximize** the chance of **finding software errors**.

1. Equivalence Partitioning (EP)
2. Boundary Value Analysis (BVA)
3. Category Partition Method (CPM)
4. Combinatorial Testing (CT)
 - Covering Array (CA)
 - Fault Detection Effectiveness
 - Greedy Algorithm – IPOG Strategy
 - Greedy vs. Meta-heuristic

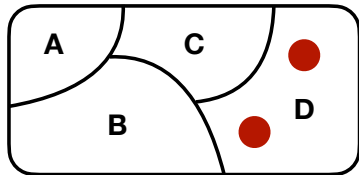
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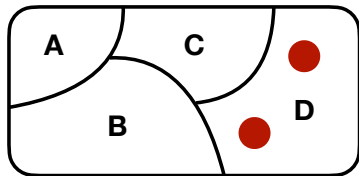
- **Equivalence partitioning** is a black-box testing technique that divides the input domain of a program into **equivalence classes**.



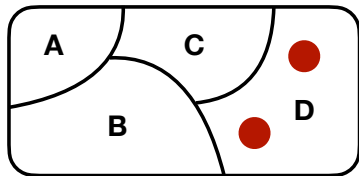
- **Equivalence partitioning** is a black-box testing technique that divides the input domain of a program into **equivalence classes**.
- The technique is based on the observation that the program should behave the same way for all members of an equivalence class.



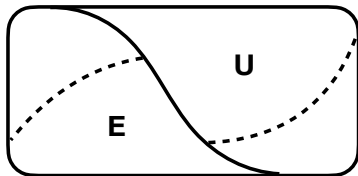
- If one test case in an equivalence class reveals an error, it is likely that other test cases in the **same equivalence class** will also reveal the **same error**.



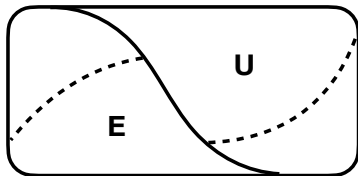
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- The idea is to **reduce** the number of test cases by selecting **one test case** from each equivalence class.
- Then, how to define the equivalence classes?



- One possible way to define the equivalence classes is to divide the input domain into **expected** and **unexpected** inputs.
 - **Expected (E)** or legal inputs
 - **Unexpected (U)** or illegal inputs



- One possible way to define the equivalence classes is to divide the input domain into **expected** and **unexpected** inputs.
 - **Expected (E)** or legal inputs
 - **Unexpected (U)** or illegal inputs
- We can further divide the expected inputs into smaller equivalence classes.

Example

Consider a program that takes a **password** as input. The length of the password must be between 6 and 20 characters.

- We can divide the input domain into two equivalence classes:
 - $E = \{ \text{a password } p \mid 6 \leq |p| \leq 20 \}$
 - $U = \{ \text{a password } p \mid |p| < 6 \vee |p| > 20 \}$

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- We can divide it more finely:
 - $E_1 = \{ \text{a password } p \mid 6 \leq |p| \leq 10 \}$ for *weak passwords*
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- We can select one test case from each equivalence class.

$$I = \{p_1, p_2, p_3, p_4, p_5\}$$

such that $|p_1| = 7$, $|p_2| = 13$, $|p_3| = 18$, $|p_4| = 3$, $|p_5| = 40$

- There are **many ways** to partition the input domain.

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Partition testing can be better, worse, or the same as random testing, depending on how the partitioning is done.¹

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- They usually occur due to **off-by-one** errors caused by misunderstanding the **boundary conditions**.
- It is **simple** but actually **very common**.

```
for (let i = 0; i < 10; i++) {  
    /* body of the loop */  
}
```

CORRECT

```
for (let i = 1; i < 10; i++) {  
    /* body of the loop */  
}
```

INCORRECT

```
for (let i = 0; i <= 10; i++) {  
    /* body of the loop */  
}
```

INCORRECT

```
for (let i = 0; i < 11; i++) {  
    /* body of the loop */  
}
```

INCORRECT

Off-by-one Errors – Fencepost error

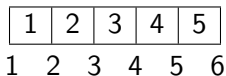
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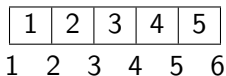
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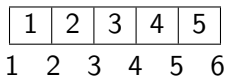
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`linspace(a, b, n)` in MATLAB is a linear interpolation function that generates a row vector of n **points** instead of n **intervals** between a and b .

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```
linspace(0, 10, 5) == [0, 2.5, 5, 7.5, 10]
                   != [0, 2, 4, 6, 8, 10]
```

```
void foo (char *s)
{
    char buf[15];
    memset(buf, 0, sizeof(buf));
    // Final parameter should be: sizeof(buf)-1
    strncpy(buf, s, sizeof(buf));
}
```

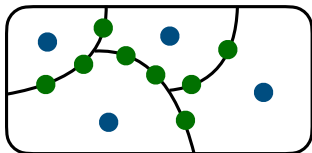
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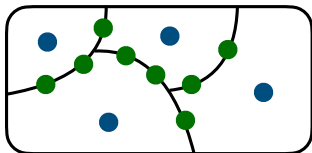
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- For example, we need to subtract 1 byte from the length of the buffer in `strncpy` but not in `fgets` or `strncpy`.
- So, the programmer has to remember for which functions they need to subtract 1.



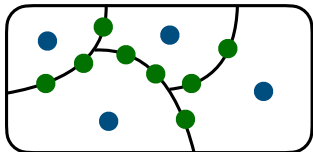
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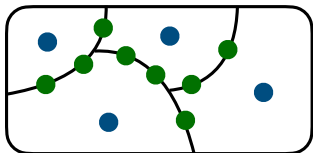
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- The technique is based on the observation that the program is more likely to fail at the **boundaries** of the input domain.
- It is usually used in combination with **equivalence partitioning**.

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- We can select test cases at the boundaries of the equivalence classes.

$$I = \{p_1, p_2, p_3, p_4, p_5, p_6, p_7, p_8\}$$

such that

$$\begin{array}{cccc} |p_1| = 5 & |p_2| = 6 & |p_3| = 10 & |p_4| = 11 \\ |p_5| = 15 & |p_6| = 16 & |p_7| = 20 & |p_8| = 21 \end{array}$$

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- **Category partition method (CPM)** is a black-box testing technique that systematically generates test cases by considering the combinations of the categories of the input domain.
 - ① Analyze **specification**
 - ② Identify **parameters** and **environments**
 - ③ Identify **categories** for each parameter and environment
 - ④ **Partition** categories into equivalence classes
 - ⑤ Identify **constraints**
 - ⑥ **Generate** test cases

Example

Unix command `grep` searches for files in a directory hierarchy with the following syntax:

```
grep <pattern> <filename>
```

For example,

- `grep park myfile` displays all lines in `myfile` that contain the word "park".
- `grep "hello world" myfile` displays all lines in `myfile` that contain the phrase "hello world".
- `grep " said \"hello \" myfile` displays all lines in `myfile` that contain the phrase " said "hello ".

Perform category partition method for the `grep` command.

① Analyze **specification**

② Identify **parameters** and **environments**

- **Parameters** – (1) <pattern> and (2) <filename>
 - The <pattern> is a pattern to search for.
 - To include spaces in the pattern, it must be enclosed in quotes (").
 - To include a quotation mark in the pattern, it must be escaped with a backslash (\").
 - ...
- **Environments** – (3) file contents
 - ...

③ Identify **categories** for each parameter and environment

① **Parameter** – `<pattern>`

- **Size**
- **Quotation marks**
- **Embedded spaces**
- **Embedded quotation marks**

② **Parameter** – `<filename>`

- **Validity**

③ **Environment** – file contents

- **Number of occurrences of the pattern**
- **Number of occurrences of the pattern in a line**

④ **Partition** categories into equivalence classes

① **Parameter** – `<pattern>`

- **Size** – 0 / 1 / ≥ 2
- **Quotation marks** – quoted (Q) / unquoted (U) / improper (I)
- **Embedded spaces** – none (N) / single (S) / multiple (M)
- **Embedded quotation marks** – none (N) / single (S) / multiple (M)

② **Parameter** – `<filename>`

- **Validity** – exists (E) / not exists (N) / omitted (O)

③ **Environment** – file contents

- **Number of occurrences of the pattern** – 0 / 1 / ≥ 2
- **Number of occurrences of the pattern in a line** – 0 / 1 / ≥ 2

Category Partition Method (CPM)

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- For example, no embedded space for unquoted pattern.

unquoted (U) $\Rightarrow \Leftarrow$ single (S) for **embedded spaces**

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⑥ **Generate** test cases

- Pick one **test case** from each combination **satisfying** the constraints.

Size	Q	Space	Emb. Q	Valid	Occur	Occur
0	Q	N	N	E	0	0
1	U	S	S	N	1	1
≥ 2	I	M	M	O	≥ 2	≥ 2

```
grep "hello world" myfile # `myfile` is an empty file
```

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 - For example, we need 1,799,736,525 test cases required for the following airport system:

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- **Combinatorial testing (CT)** or **combinatorial interaction testing (CIT)** constructs test cases by considering the **interactions** between the parameters.

Definition (Interaction)

For k parameters with v values each, a *t*-**way interaction** is a combination of values for t parameters.

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Definition (Covering Array (CA))

A **covering array** $A = CA(N; t, k, v)$ is a $N \times k$ matrix such that every field is an element from the set $[0, v - 1]$, and every t -way interaction is covered at least once by a row of A .

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A	B	C
0	0	0
1	1	1



$CA(N = 4; t = 2, k = 3, v = 2)$

A	B	C
0	0	0
0	1	1
1	0	1
1	1	0

Definition (Mixed Covering Array (MCA))

A **mixed covering array** $A = CA(N; t, k, v = (v_1, v_2, \dots, v_k))$ is a $N \times k$ matrix such that every field in the i -th column is an element from the set $[0, v_i - 1]$, and every t -way interaction is covered at least once by a row of A .

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$$CA(N = 6; t = 2, k = 3, v = (2, 2, 3))$$

A	B	C
0	0	0
1	1	1
		2



A	B	C
0	0	0
0	1	1
1	0	2
1	1	0
1	0	1
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Definition (Constraint Mixed Covering Array (CMCA))

A **mixed covering array** $A = CA(N; t, k, v = (v_1, v_2, \dots, v_k), P)$ is a $N \times k$ matrix such that every field in the i -th column is an element from the set $[0, v_i - 1]$, and every **valid** t -way interaction is covered at least once by a row of A . We say that a t -way interaction is **valid** if it satisfies the predicate P .

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A	B	C
0	0	0
1	1	1
		2

 \Rightarrow
 $CA(N = 5; t = 2, k = 3, v = (2, 2, 3), P)$

A	B	C
0	1	1
1	0	2
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$$P(x, y) = x + y > 0$$

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Pairwise testing produces 5 test cases for the following system:

A	B	C
0	0	0
1	1	1
		2



$CA(N = 5; t = 2, k = 3, v = (2, 2, 3), P)$

A	B	C
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0	0	0
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		2



$CA(N = 5; t = 2, k = 3, v = (2, 2, 3), P)$

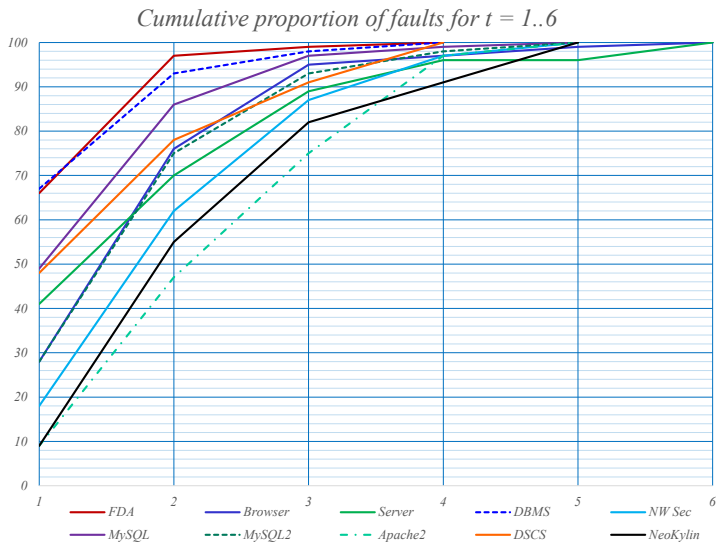
A	B	C
0	1	1
1	0	2
1	1	0
1	0	1
0	1	2

$$P(x, y) = x + y > 0$$

- Pairwise testing is a **good trade-off** between test effort and test effectiveness.
 - For a system with 20 parameters each with 15 values, **pairwise testing** only requires 412 tests, whereas exhaustive testing requires $15^{20} = 3.5 \times 10^{25}$ tests.

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 - For a system with 20 parameters each with 15 values, **pairwise testing** only requires 412 tests, whereas exhaustive testing requires $15^{20} = 3.5 \times 10^{25}$ tests.
- Is higher strength always better for fault detection?
- It depends on the target program, but we can analyze the **general trend** against **a set of known faults**.
 - **Pairwise testing** discovers at least **53%** of the known faults.
 - **6-way testing** discovers **100%** of the known faults.



“Combinatorial Methods in Software Testing” by Rick Kuhn, NIST,

- The problem of generating a minimum covering array is **NP-complete**.
 - It can be reduced to the **vertex cover problem**.

²[ECBS'07] LEI, Yu, et al. "*IPOG: A general strategy for t-way software testing*."

- The problem of generating a minimum covering array is **NP-complete**.
 - It can be reduced to the **vertex cover problem**.
- Let's learn a **polynomial time** greedy algorithm called **IPOG (In-Parameter-Order-General)**² that generates a covering array with a strength t . It is not optimal but practical.

²[ECBS'07] LEI, Yu, et al. "IPOG: A general strategy for t -way software testing.

- 1 Initialize **test set** ts to be an empty set.
- 2 **Parameters** are P_1, P_2, \dots, P_k .
- 3 Add a test into ts for **all interactions of the first t parameters**.
- 4 **for** ($i = t + 1; i \leq n; i++$) (**Horizontal Growth**)
 - 1 Let π be the **set of t -way interactions** involving **parameter P_i** and $t - 1$ parameters among the first $i - 1$ parameters.
 - 2 **for** (test $\gamma = (v_1, v_2, \dots, v_{i-1}) \in ts$)
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Example

We want to **pairwise testing** for the following system:

P_1	P_2	P_3
0	0	0
1	1	1
		2

Adding all combinations of values between the first 2 parameters:

$$ts =$$

P_1	P_2
0	0
0	1
1	0
1	1

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- ④ **for** ($i = t + 1; i \leq n; i++$) (**Horizontal Growth**)
 - ① Let π be the **set of t -way interactions** involving **parameter P_i** and $t - 1$ parameters among the first $i - 1$ parameters.

Greedy Algorithm – IPOG Strategy

Set π as pairs to cover involving P_3 :

$$\pi =$$

P_1	P_2	P_3
0		0
	0	0
0		1
	0	1
0		2
	0	2
1		0
	1	0
1		1
	1	1
1		2
	1	2

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Adding values for P_3 in ts :

$$ts =$$

P_1	P_2	P_3
0	0	
0	1	
1	0	
1	1	

$$\pi =$$

P_1	P_2	P_3
0		0
	0	0
0		1
	0	1
0		2
	0	2
1		0
	1	0
1		1
	1	1
1		2
	1	2

Adding values for P_3 in ts :

$$ts =$$

P_1	P_2	P_3
0	0	0
0	1	
1	0	
1	1	

$$\pi =$$

P_1	P_2	P_3
0		0
	0	0
0		1
	0	1
0		2
	0	2
1		0
	1	0
1		1
	1	1
1		2
	1	2

Adding values for P_3 in ts :

$$ts =$$

P_1	P_2	P_3
0	0	0
0	1	1
1	0	
1	1	

$$\pi =$$

P_1	P_2	P_3
0		0
	0	0
0		1
	0	1
0		2
	0	2
1		0
	1	0
1		1
	1	1
1		2
	1	2

Adding values for P_3 in ts :

$$ts =$$

P_1	P_2	P_3
0	0	0
0	1	1
1	0	1
1	1	

$$\pi =$$

P_1	P_2	P_3
0		0
	0	0
0		1
	0	1
0		2
	0	2
1		0
	1	0
1		1
	1	1
1		2
	1	2

Adding values for P_3 in ts :

$$ts =$$

P_1	P_2	P_3
0	0	0
0	1	1
1	0	1
1	1	0

$$\pi =$$

P_1	P_2	P_3
0		0
	0	0
0		1
	0	1
0		2
	0	2
1		0
	1	0
1		1
	1	1
1		2
	1	2

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Extending ts :

$$ts =$$

P_1	P_2	P_3
0	0	0
0	1	1
1	0	1
1	1	0

$$\pi =$$

P_1	P_2	P_3
0		0
	0	0
0		1
	0	1
0		2
	0	2
1		0
	1	0
1		1
	1	1
1		2
	1	2

Extending ts :

$$ts =$$

P_1	P_2	P_3
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1	0	1
1	1	0
0	0	2

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P_1	P_2	P_3
0		0
	0	0
0		1
	0	1
0		2
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1		0
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P_1	P_2	P_3
0		0
	0	0
0		1
	0	1
0		2
	0	2
1		0
	1	0
1		1
	1	1
1		2
	1	2

- Simulated Annealing, a type of local search algorithm, has been proven to be effective against CIT.³

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Size comparison

Subject	Greedy	Meta-heuristic
SPIN-S	27	19
SPIN-V	42	36
GCC	24	21
Apache	42	32
Bugzilla	21	16

Time (sec.) comparison

Subject	Greedy	Meta-heuristic
SPIN-S	0.2	8.6
SPIN-V	11.3	102.1
GCC	204	1902.0
Apache	76.4	109.1
Bugzilla	1.9	9.1

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1. Equivalence Partitioning (EP)
2. Boundary Value Analysis (BVA)
3. Category Partition Method (CPM)
4. Combinatorial Testing (CT)
 - Covering Array (CA)
 - Fault Detection Effectiveness
 - Greedy Algorithm – IPOG Strategy
 - Greedy vs. Meta-heuristic

- Random Testing

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