# <span id="page-0-0"></span>Lecture 26 – Type Inference (2) COSE212: Programming Languages

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**APLRG** 

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• **Type inference** is the process of automatically inferring the types of expressions.



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- We have seen three examples to learn how the type inference works.

/\* RFAE \*/ def sum(x) = if  $(x < 1)$  0 else x + sum(x - 1); sum

/\* FAE \*/ val app = n => f => f(n); app(42)(x => x)

/\* FAE \*/ val id = x => x; val n = id(42); val b = id(true); b



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- In this lecture, let's learn the details of the type inference algorithm.
- **TIFAE** TRFAE with **type inference**.
	- **Type Checker** and **Typing Rules** with **Type Inference**
	- Interpreter and Natural Semantics

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# Type Checker and Typing Rules

Let's **1** design **typing rules** of TIFAE to define when an expression is well-typed in the form of:

and 2 implement a **type checker** in Scala according to typing rules:

def typeCheck(expr: Expr, tenv: TypeEnv): Type = ???

The type checker returns the **type** of *e* if it is well-typed, or rejects it and throws a **type error** otherwise.

We will keep track of the **variable types** using a **type environment** Γ as a mapping from variable names to their types.

$$
\text{Type Environments}\hspace{2em} \Gamma \hspace{2em}\in\hspace{2em} \mathbb{T} = \mathbb{X} \xrightarrow{\text{fin}} \mathbb{T} \hspace{2em} (\text{TypeEnv})
$$

type TypeEnv = Map[String, Type]





#### <span id="page-8-0"></span>Recall: Example 1 – sum



In addition, we need to keep track of the **solution** for **type constraints** over **type variables** to infer the types of expressions.

/\* RFAE \*/ def sum(x) = if (x < 1) 0 else x + sum(x - 1); sum



## Solutions for Type Constraints



A **solution** is a mapping from **type variables** to **types** or •.

Types  $\mathbb{T} \ni \tau ::= \text{num} | \text{bool} | \tau \rightarrow \tau | \alpha$  (Type)  $\textsf{Solutions} \qquad \qquad \psi \ \ \in \ \Psi = \mathbb{X}_{\alpha} \xrightarrow{\mathrm{fin}} (\mathbb{T} \uplus \{\bullet\}) \quad \textsf{(Solution)}$  $Type\ Variables \qquad \alpha \in \mathbb{X}_{\alpha}$  (Int)

type Solution = Map[Int, Option[Type]]

Note that • (None) represents a **not yet solved** (**free**) type variable.

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type Solution = Map[Int, Option[Type]]

Note that • (None) represents a **not yet solved** (**free**) type variable.

Now, we have new forms of **type checker** and **typing rules**.

def typeCheck(expr: Expr, tenv: TypeEnv, sol: Solution): (Type, Solution) = ???

$$
\Gamma,\overline{\psi} \vdash e : \tau,\overline{\psi}
$$

Similar to the memory passing in MFAE for mutation, we will pass the solution  $\psi$  and update it during type checking.

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#### <span id="page-11-0"></span>Numbers



def typeCheck(e: Expr, tenv: TypeEnv, sol: Solution): (Type, Solution) = e match ... case  $Num(n) \Rightarrow (NumT, sol)$ 

$$
|\Gamma,\psi \vdash e:\tau,\psi \, \big|
$$

$$
\tau\mathrm{-Num} \; \overline{\Gamma,\psi \vdash n : \mathrm{num}, \psi}
$$

### <span id="page-12-0"></span>**Additions**



```
def typeCheck(e: Expr, tenv: TypeEnv, sol: Solution): (Type, Solution) = e match
  ...
  case Add(1, r) =>
    val (lty, sol1) = typeCheck(1, \text{tenv}, \text{sol})val (rty, sol2) = typeCheck(r, \text{tenv}, \text{sol1})val sol3 = \text{unify}(\text{lty}, \text{NumT}, \text{sol2})val sol4 = unify(rty, NumT, sol3)(NumT, sol4)
```

$$
\Gamma,\psi \vdash e:\tau,\psi
$$

$$
\Gamma, \psi_0 \vdash e_1 : \tau_1, \psi_1 \qquad \Gamma, \psi_1 \vdash e_2 : \tau_2, \psi_2
$$
\n
$$
\tau-\text{Add} \frac{\text{unify}(\tau_1, \text{num}, \psi_2) = \psi_3 \qquad \text{unify}(\tau_2, \text{num}, \psi_3) = \psi_4}{\Gamma, \psi_0 \vdash e_1 + e_2 : \text{num}, \psi_4}
$$

The unify function that takes two types must be the same and updates the given solution. We will see how it works later.

### <span id="page-13-0"></span>**Conditionals**



```
def typeCheck(e: Expr, tenv: TypeEnv, sol: Solution): (Type, Solution) = e match
  ...
  case If(c, t, e) =>
    val (cty, sol1) = typeCheck(c, tenv, sol)
    val (tty, sol2) = typeCheck(t, \text{tenv}, \text{sol1})val (ety, sol3) = typeCheck(e, tenv, sol2)
    val sol4 = unify(cty, BoolT, sol3)
    val sol5 = \text{unify}(\text{tty}, \text{ety}, \text{sol4})(tty, sol5)
```

$$
\Gamma,\psi \vdash e:\tau,\psi
$$

$$
\Gamma, \psi \vdash e_c : \tau_c, \psi_c \qquad \Gamma, \psi_c \vdash e_t : \tau_t, \psi_t \qquad \Gamma, \psi_t \vdash e_e : \tau_e, \psi_e
$$
\n
$$
\tau-\text{If } \frac{\text{unify}(\tau_c, \text{bool}, \psi_e) = \psi' \qquad \text{unify}(\tau_t, \tau_e, \psi') = \psi''}{\Gamma, \psi \vdash \text{if } (e_c) \ e_t \text{ else } e_e : \tau_t, \psi''}
$$

#### <span id="page-14-0"></span>Immutable Variable Defs. and Identifier Lookup **APLRG**

```
def typeCheck(e: Expr, tenv: TypeEnv, sol: Solution): (Type, Solution) = e match
  ...
  case Val(x, e, b) =>
    val (ety, sol1) = typeCheck(e, tenv, sol)
    typeCheck(b, tenv + (x -> ety), sol1)case Id(x) \Rightarrowval ty = tenv.getOrElse(x, error(s"free identifier: x''))
    (ty, sol)
```

$$
\Gamma,\psi \vdash e:\tau,\psi
$$

$$
\tau-\mathtt{Val}\ \frac{\Gamma,\psi_0\vdash e_1:\tau_1,\psi_1\qquad\Gamma[x:\tau_1],\psi_1\vdash e_2:\tau_2,\psi_2}{\Gamma,\psi_0\vdash \mathtt{val}\ x=e_1;\ e_2:\tau_2,\psi_2}
$$

$$
\tau\text{--Id}\;\frac{x\in\text{Domain}(\Gamma)}{\Gamma,\psi\vdash x:\Gamma(x),\psi}
$$

## <span id="page-15-0"></span>Function Definitions



```
def typeCheck(e: Expr, tenv: TypeEnv, sol: Solution): (Type, Solution) = e match
  ...
  case Fun(p, b) \Rightarrowval (pty, sol1) = newTypeVar(sol)
    val (rty, sol2) = typeCheck(b, tenv + (p \rightarrow pty), sol1)
    (ArrowT(pty, rty), sol2)
```

$$
\Gamma,\psi \vdash e:\tau,\psi
$$

$$
\tau\!-\!\mathrm{Fun}\;\frac{\alpha_p\notin\psi\qquad\Gamma[x:\alpha_p],\psi[\alpha_p\mapsto\bullet]\vdash e:\tau,\psi'}{\Gamma,\psi\vdash\lambda x.e:\alpha_p\to\tau,\psi'}
$$

We need to introduce a **new type variable**  $\alpha_n$  for the parameter *x*.

### <span id="page-16-0"></span>Recursive Function Definitions



```
def typeCheck(e: Expr, tenv: TypeEnv, sol: Solution): (Type, Solution) = e match
  ...
  case Rec(f, p, b, s) =>
    val (pty, sol1) = newTypeVar(sol)
    val (rty, sol2) = newTypeVar(sol1)
    val fty = ArrowT(pty, rty)
    val tenv1 = tenv + (f \rightarrow fty)val tenv2 = tenv1 + (p \rightarrow pty)val (bty, sol3) = typeCheck(b, tenv2, sol2)
    val sol4 = \text{unify}(bty, rty, sol3)typeCheck(s, tenv1, sol4)
```

$$
|\Gamma,\psi \vdash e:\tau,\psi \, \big|
$$

$$
\alpha_p, \alpha_r \notin \psi \qquad \alpha_p \neq \alpha_r \qquad \Gamma_1 = \Gamma[x_f : (\alpha_p \to \alpha_r)]
$$

$$
\Gamma_2 = \Gamma_1[x_p : \alpha_p] \qquad \Gamma_2, \psi[\alpha_p \mapsto \bullet, \alpha_r \mapsto \bullet] \vdash e_b : \tau_b, \psi_b
$$

$$
\tau-\text{Rec} \qquad \frac{\text{unify}(\tau_b, \alpha_r, \psi_b) = \psi_r \qquad \Gamma_1, \psi_r \vdash e_s : \tau_s, \psi_s}{\Gamma, \psi \vdash \text{def } x_f(x_p) = e_b; \ e_s : \tau_s, \psi_s}
$$

## <span id="page-17-0"></span>Function Applications



```
def typeCheck(e: Expr, tenv: TypeEnv, sol: Solution): (Type, Solution) = e match
  ...
  case App(f, a) =>
    val (fty, sol1) = typeCheck(f, tenv, sol)
    val (aty, sol2) = typeCheck(a, tenv, sol1)
    val (rty, sol3) = newTypeVar(sol2)
    val sol4 = unify(ArrowT(aty, rty), fty, sol3)
    (rty, sol4)
```

$$
\Gamma,\psi \vdash e:\tau,\psi
$$

$$
\Gamma, \psi \vdash e_f : \tau_f, \psi_f \qquad \Gamma, \psi_f \vdash e_a : \tau_a, \psi_a
$$
  

$$
\tau \vdash \text{App} \frac{\alpha_r \notin \psi_a \qquad \text{unify}(\tau_a \to \alpha_r, \tau_f, \psi_a[\alpha_r \mapsto \bullet]) = \psi'}{\Gamma, \psi \vdash e_f(e_a) : \alpha_r, \psi'}
$$

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#### Definition (Type Unification)

**Type unification** is the process of updating a solution to make two types equal. If the types are not unifiable, then this process fails and throws an exception.

unify :  $(\mathbb{T} \times \mathbb{T} \times \Psi) \rightarrow \Psi$ 

For example, if we unify a type variable  $\alpha$  and the number type num, the solution  $[\alpha \mapsto \bullet]$  is updated to  $[\alpha \mapsto \text{num}]$ .

unify $(\alpha, \text{num}, \varnothing) = [\alpha \mapsto \text{num}]$ 



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unify $(\alpha, \text{num}, \varnothing) = [\alpha \mapsto \text{num}]$ 

Before, we define the type unification, we need to define the **type resolving** and **occurrence checking** functions.

- **1 Type resolving** is the process of recursively resolving a type variable to its representative type to deal with the **type aliasing**.
- **2 Occurrence checking** is the process of checking whether a type variable occurs in a type to detect **recursive types**.



<span id="page-21-0"></span>To understand why we need the **type resolving** function, let's consider the following example:

 $unify(\alpha_1, num, \psi_1) = \psi_2$ 





To understand why we need the **type resolving** function, let's consider the following example:  $\text{unify}(\alpha_1, \text{num}, \psi_1) = \psi_2$ 

Solution  
\n
$$
\psi_1 = \frac{\frac{\text{Solution}}{\frac{\text{X}_{\alpha} \quad \text{T}}{\text{X}_{\alpha}}}}{\frac{\alpha_1 \quad \alpha_2}{\alpha_3 \quad \text{A}} \qquad \psi_2 = \frac{\frac{\text{X}_{\alpha} \quad \text{T}}{\text{X}_{\alpha} \quad \text{T}}}{\frac{\alpha_1 \quad \text{num}}{\alpha_2 \quad \alpha_3}}}{\frac{\alpha_2 \quad \alpha_3}{\alpha_3 \quad \text{A}}}
$$



To understand why we need the **type resolving** function, let's consider the following example:  $\text{unify}(\alpha_1, \text{num}, \psi_1) = \psi_2$ 

> $\psi_1 =$ Solution  $\mathbb{X}_{\alpha}$  | T  $\alpha_1 \mid \alpha_2$  $\alpha_2 \mid \alpha_3$  $α_3$  $\psi_2 =$ Solution  $\mathbb{X}_{\alpha}$  | T  $\alpha_1$  | num  $\alpha_2 \mid \alpha_3$ *α*<sup>3</sup> •

If we update  $\alpha_1$  to num in the solution  $\psi_2$ , it misses the information that  $\alpha_2$  and  $\alpha_3$  are also num.



To understand why we need the **type resolving** function, let's consider the following example:

 $\text{unify}(\alpha_1, \text{num}, \psi_1) = \psi_2$ 



If we directly update  $\alpha_1$  to num in the solution  $\psi_2$ , it misses the information that  $\alpha_2$  and  $\alpha_3$  are also num.

Instead, we need to **resolve** the type variable  $\alpha_1$  to find its **representative type** (i.e., *α*3) and unify it with num to deal with the **type aliasing**.



#### We can define the **type resolving** function as follows:

$$
\mathtt{resolve} : (\mathbb{T} \times \Psi) \to \mathbb{T}
$$

$$
\texttt{resolve}(\tau,\psi) = \left\{ \begin{array}{ll} \texttt{resolve}(\tau',\psi) & \text{if } \tau = \alpha \wedge \psi(\alpha) = \tau' \\ \tau & \text{otherwise} \end{array} \right.
$$

and implement it in Scala as follows:

```
def resolve(ty: Type, sol: Solution): Type = ty match
  case VarT(k) \Rightarrow sol(k) match
    case Some(ty) \Rightarrow resolve(ty, sol)case None => ty
  case => ty
```


#### <span id="page-26-0"></span>Let's understand why we need the **occurrence checking** function:

 $\texttt{unify}(\alpha_1, \texttt{num} \rightarrow \alpha_1, \psi) = \psi'$ 

Can we unify  $\alpha_1$  and num  $\rightarrow \alpha_1$ ?



Let's understand why we need the **occurrence checking** function:

 $\texttt{unify}(\alpha_1, \texttt{num} \rightarrow \alpha_1, \psi) = \psi'$ 

Can we unify  $\alpha_1$  and num  $\rightarrow \alpha_1$ ? **No!** because it requires **recursive types** not supported in our type system.



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Can we unify  $\alpha_1$  and num  $\rightarrow \alpha_1$ ? **No!** because it requires **recursive types** not supported in our type system.

Let's define the **occurrence checking** function to detect type constraints that require recursive types

$$
\text{occur}: (\mathbb{X}_{\alpha} \times \mathbb{T} \times \Psi) \to \text{bool} \n\text{occur}(\alpha, \tau, \psi) = \left\{ \begin{array}{ll} \text{true} & \text{if } \tau = \alpha \\ \text{occur}(\alpha, \tau_p, \psi) \vee \text{occur}(\alpha, \tau_r, \psi) & \text{if } \tau = (\tau_p \to \tau_r) \\ \text{false} & \text{otherwise} \end{array} \right.
$$



Let's understand why we need the **occurrence checking** function:

 $\texttt{unify}(\alpha_1, \texttt{num} \rightarrow \alpha_1, \psi) = \psi'$ 

Can we unify  $\alpha_1$  and  $\text{num} \rightarrow \alpha_1$ ? **No!** because it requires **recursive types** not supported in our type system.

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$$

and implement it in Scala as follows:

def occurs(k: Int, ty: Type, sol: Solution): Boolean = resolve(ty, sol) match case  $VarT(1) \Rightarrow k == 1$ case ArrowT(pty, rty) => occurs(k, pty, sol) || occurs(k, rty, sol)  $case \rightharpoonup$  => false



<span id="page-30-0"></span>Using the **type resolving** and **occurrence checking** functions, we could define the **type unification** as a partial function:

unify :  $(\mathbb{T} \times \mathbb{T} \times \Psi) \rightarrow \Psi$ 

.



3



Using the **type resolving** and **occurrence checking** functions, we could define the **type unification** as a partial function:

$$
\texttt{unify} : (\mathbb{T} \times \mathbb{T} \times \Psi) \rightharpoonup \Psi \, \big| \,
$$

 ${\tt unify}(\tau_1,\tau_2,\psi)=$  $\sqrt{ }$  $\int$  $\overline{\mathcal{L}}$ 

 $\textsf{where} \; \tau_1' = \texttt{resolve}(\tau_1, \psi) \; \textsf{and} \; \tau_2' = \texttt{resolve}(\tau_2, \psi).$ 

**1** First, it resolves the types  $\tau_1$  and  $\tau_2$  with the current solution  $\psi$  into  $\tau'_1$  and  $\tau'_2$  using the  $\tt type$  resolving function  $\tt resolve$ . 2



Using the **type resolving** and **occurrence checking** functions, we could define the **type unification** as a partial function:

$$
\texttt{unify} : (\mathbb{T} \times \mathbb{T} \times \Psi) \rightharpoonup \Psi \, \big| \,
$$

 ${\tt unify}(\tau_1,\tau_2,\psi)=$  $\sqrt{ }$  $\int$  $\begin{cases} \psi[\alpha \mapsto \tau'_2] \\ \psi[\alpha \mapsto \tau'_1] \end{cases}$  $\left[\begin{array}{cc} \gamma' \\ 2 \end{array}\right]$  if  $\tau$  $\alpha'_{1} = \alpha \wedge \neg \text{occur}(\alpha, \tau'_{2})$  $\psi[\alpha \mapsto \tau'_1]$  $\left[ \begin{array}{c} I_1 \\ 1 \end{array} \right]$  if  $\tau$  $\alpha'_2 = \alpha \wedge \neg \text{occur}(\alpha, \tau'_1)$ 

 $\textsf{where} \; \tau_1' = \texttt{resolve}(\tau_1, \psi) \; \textsf{and} \; \tau_2' = \texttt{resolve}(\tau_2, \psi).$ 

- **1** First, it resolves the types  $\tau_1$  and  $\tau_2$  with the current solution  $\psi$  into  $\tau'_1$  and  $\tau'_2$  using the  $\tt type$  resolving function  $\tt resolve$ .
- $\, {\bf 2} \,$  If one of  $\tau'_1$  or  $\tau'_2$  is a type variable, it checks recursive types using the **occurrence checking** and updates the solution of the type variable.



Using the **type resolving** and **occurrence checking** functions, we could define the **type unification** as a partial function:

unify :  $(\mathbb{T} \times \mathbb{T} \times \Psi) \rightarrow \Psi$ 

$$
\begin{array}{ll} \displaystyle \inf \mathbf{y}(\tau_1,\tau_2,\psi)= \\[1.5ex] \displaystyle \psi & \text{if } \tau_1'=\texttt{num} \wedge \tau_2'=\texttt{num} \\[1.5ex] \displaystyle \psi & \text{if } \tau_1'=\texttt{bool} \wedge \tau_2'=\texttt{bool} \\[1.5ex] \displaystyle \inf \mathbf{y}(\tau_{1,r},\tau_{2,r},\texttt{unify}(\tau_{1,p},\tau_{2,p},\psi)) & \text{if } \tau_1'=(\tau_{1,p} \rightarrow \tau_{1,r}) \wedge \tau_2'=(\tau_{2,p} \rightarrow \tau_{2,r}) \\[1.5ex] \displaystyle \psi & \text{if } \tau_1'=\alpha=\tau_2' \\[1.5ex] \displaystyle \psi[\alpha \mapsto \tau_2'] & \text{if } \tau_1'=\alpha \wedge \neg \texttt{occur}(\alpha,\tau_2') \\[1.5ex] \displaystyle \psi[\alpha \mapsto \tau_1'] & \text{if } \tau_2'=\alpha \wedge \neg \texttt{occur}(\alpha,\tau_1') \end{array}
$$

 $\textsf{where} \; \tau_1' = \texttt{resolve}(\tau_1, \psi) \; \textsf{and} \; \tau_2' = \texttt{resolve}(\tau_2, \psi).$ 

**1** First, it resolves the types  $\tau_1$  and  $\tau_2$  with the current solution  $\psi$  into  $\tau'_1$  and  $\tau'_2$  using the  $\tt type$  resolving function  $\tt resolve$ .

 $\, {\bf 2} \,$  If one of  $\tau'_1$  or  $\tau'_2$  is a type variable, it checks recursive types using the **occurrence checking** and updates the solution of the type variable.  $\,$  Otherwise, it checks  $\tau^\prime_1$  and  $\tau^\prime_2$  are equal or recursively unifies them.



$$
\begin{array}{ll}\text{unify}(\tau_1,\tau_2,\psi)=\\ \begin{cases} \psi & \text{if } \tau_1'=\text{num}\wedge\tau_2'=\text{num}\\ \psi & \text{if } \tau_1'=\text{bool}\wedge\tau_2'=\text{bool}\\ \text{unify}(\tau_{1,r},\tau_{2,r},\text{unify}(\tau_{1,p},\tau_{2,p},\psi)) & \text{if } \tau_1'=(\tau_{1,p}\rightarrow\tau_{1,r})\wedge\tau_2'=(\tau_{2,p}\rightarrow\tau_{2,r})\\ \psi & \text{if } \tau_1'=\alpha=\tau_2'\\ \psi[\alpha\mapsto\tau_2'] & \text{if } \tau_1'=\alpha\wedge\neg\text{occur}(\alpha,\tau_2')\\ \psi[\alpha\mapsto\tau_1'] & \text{if } \tau_2'=\alpha\wedge\neg\text{occur}(\alpha,\tau_1')\end{cases}\end{array}
$$

 $\textsf{where} \; \tau_1' = \texttt{resolve}(\tau_1, \psi) \; \textsf{and} \; \tau_2' = \texttt{resolve}(\tau_2, \psi).$ 

And, we can implement the **type unification** function in Scala as follows:

```
def unify(lty: Type, rty: Type, sol: Solution): Solution =
  (resolve(lty, sol), resolve(rty, sol)) match
    case (NumT, NumT) => sol
    case (BoolT, BoolT) => sol
    case (ArrowT(1pty, 1rty), ArrowT(rtty, rrty)) =>
      unify(lrty, rrty, unify(lpty, rpty, sol))
    case (VarT(k), VarT(1)) if k == 1 => solcase (VarT(k), rty) if locurs(k, rtv, sol) \Rightarrow sol + (k \Rightarrow Some(rtv)case (lty, VarT(k)) if locours(k, lty, sol) \Rightarrow sol + (k \Rightarrow Some(lty))case _ => error(s"Cannot unify ${lty.str} and ${rty.str}")
```
## <span id="page-35-0"></span>Contents



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#### <span id="page-36-0"></span>Recall: Example 3 – id





Let's **generalize** the type T1 => T1 into a **polymorphic type** for id with **type variable** T1 as a **type parameter**. We call this **let-polymorphism** because it only introduces polymorphism for the let-binding  $(e.g., val)$ .

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## Type Environment with Type Schemes



We need to extend the **type environment** with **type schemes**, restricted forms of polymorphic types.

Type Environments  $\mathbb{\Gamma} = \mathbb{X} \xrightarrow{\mathrm{fin}} \mathbb{T}^\forall$ **Type Schemes**  $(x^*)$ . $\tau = \tau^\forall$   $\in$   $\mathbb{T}^\forall = \mathbb{X}_\alpha^* \times \mathbb{T}$ Types  $\mathbb{T} \ni \tau ::= \text{num} | \text{bool} | \tau \rightarrow \tau | \alpha$ 

## Type Environment with Type Schemes



We need to extend the **type environment** with **type schemes**, restricted forms of polymorphic types.

Type Environments	$\Gamma \in \Gamma = \mathbb{X} \xrightarrow{\text{fin}} \mathbb{T}^{\forall}$
Type Schemes	$\forall (\alpha^*). \tau = \tau^{\forall} \in \mathbb{T}^{\forall} = \mathbb{X}_{\alpha}^* \times \mathbb{T}$
TypeS	$\mathbb{T} \ni \tau ::= \text{num} \mid \text{bool} \mid \tau \to \tau \mid \alpha$

Note that polymorphic types are not types in TIFAE, and **type schemes** are restricted forms of polymorphic types used in type environments.

## Type Environment with Type Schemes



We need to extend the **type environment** with **type schemes**, restricted forms of polymorphic types.

Type Environments	$\Gamma \in \Gamma = \mathbb{X} \xrightarrow{\text{fin}} \mathbb{T}^{\forall}$
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Note that polymorphic types are not types in TIFAE, and **type schemes** are restricted forms of polymorphic types used in type environments.

We can define the **type environment** and **type schemes** in Scala:



## Immutable Variable Defs. with Type Generalization **NPLRG**

```
def typeCheck(e: Expr, tenv: TypeEnv, sol: Solution): (Type, Solution) = e match
  ...
  case Val(x, e, b) =>
    val (ety, sol1) = typeCheck(e, tenv, sol)
    val polyty = gen(ety, tenv, sol1)
    typeCheck(b, tenv + (x -> polyty), sol1)
```

$$
\Gamma,\psi \vdash e:\tau,\psi
$$

$$
\Gamma, \psi_0 \vdash e_1 : \tau_1, \psi_1
$$
\n
$$
\tau
$$
-Val 
$$
\frac{\text{gen}(\tau_1, \Gamma, \psi_1) = \tau_1^{\forall}}{\Gamma, \psi_0 \vdash \text{val } x = e_1; \ e_2 : \tau_2, \psi_2}
$$
\n
$$
\tau
$$

We need to **generalize** the type  $\tau_1$  of the expression  $e_1$  into a **type scheme** *τ* ∀ <sup>1</sup> using the **type generalization** function gen.

## Immutable Variable Defs. with Type Generalization **NPLRG**

```
def typeCheck(e: Expr, tenv: TypeEnv, sol: Solution): (Type, Solution) = e match
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  case Val(x, e, b) =>
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    val polyty = gen(ety, tenv, sol1)
    typeCheck(b, tenv + (x -> polyty), sol1)
```

$$
\Gamma,\psi \vdash e:\tau,\psi
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$$
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\n
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$$
\n
$$
\tau
$$

We need to **generalize** the type  $\tau_1$  of the expression  $e_1$  into a **type scheme** *τ* ∀ <sup>1</sup> using the **type generalization** function gen. For example,

$$
\texttt{gen}(\alpha\rightarrow\alpha,\varnothing,[\alpha\mapsto\bullet])=\forall\alpha.(\alpha\rightarrow\alpha)
$$



#### We can define the **type generalization** function gen as follows:

 $\overline{\mathsf{gen} : (\mathbb{T} \times \mathbb{T} \times \Psi) \to \mathbb{T}^\forall}$  $gen(\tau, \Gamma, \psi) = \forall (\alpha_1, \ldots, \alpha_m) . \tau$  where  $free_\tau(\tau, \psi) \setminus free_\Gamma(\Gamma, \psi) = {\alpha_1, \ldots, \alpha_m}$ 



#### We can define the **type generalization** function gen as follows:

 $\overline{\mathsf{gen} : (\mathbb{T} \times \mathbb{T} \times \Psi) \to \mathbb{T}^\forall}$  $gen(\tau, \Gamma, \psi) = \forall (\alpha_1, \ldots, \alpha_m) . \tau$  where  $free_\tau(\tau, \psi) \setminus free_\Gamma(\Gamma, \psi) = {\alpha_1, \ldots, \alpha_m}$ 

with the following definitions of **free type variables** in each component:

$$
\textbf{free}_{\tau}(\tau,\psi) = \left\{ \begin{array}{ll} \left\{ \alpha \right\} & \text{if } \tau = \alpha \wedge \psi(\alpha) = \bullet \\ \textbf{free}_{\tau}(\tau,\psi) & \text{if } \tau = \alpha \wedge \psi(\alpha) = \bullet \\ \textbf{free}_{\tau}(\tau,\psi) & \text{if } \tau = \alpha \wedge \psi(\alpha) = \tau' \\ \textbf{free}_{\tau}(\tau_p,\psi) \cup \textbf{free}_{\tau}(\tau_r,\psi) & \text{if } \tau = (\tau_p \rightarrow \tau_r) \\ \varnothing & \text{otherwise} \end{array} \right.
$$



#### We can define the **type generalization** function gen as follows:

 $\overline{\mathsf{gen} : (\mathbb{T} \times \mathbb{T} \times \Psi) \to \mathbb{T}^\forall}$  $gen(\tau, \Gamma, \psi) = \forall (\alpha_1, \ldots, \alpha_m) . \tau$  where  $free_\tau(\tau, \psi) \setminus free_\Gamma(\Gamma, \psi) = {\alpha_1, \ldots, \alpha_m}$ 

with the following definitions of **free type variables** in each component:

$$
\text{free}_{\tau} : (\mathbb{T} \times \Psi) \to \mathcal{P}(\mathbb{X}_{\alpha})
$$
\n
$$
\text{free}_{\tau}(\tau, \psi) = \begin{cases}\n\{\alpha\} & \text{if } \tau = \alpha \land \psi(\alpha) = \bullet \\
\text{free}_{\tau}(\tau', \psi) & \text{if } \tau = \alpha \land \psi(\alpha) = \tau' \\
\text{free}_{\tau}(\tau_p, \psi) \cup \text{free}_{\tau}(\tau_r, \psi) & \text{if } \tau = (\tau_p \to \tau_r) \\
\varnothing & \text{otherwise}\n\end{cases}
$$

$$
\mathbf{free}_{\tau^{\vee}}(\forall(\alpha_1,\ldots,\alpha_m).\tau,\psi) = \mathbf{free}_{\tau}(\tau,\psi) \setminus {\alpha_1,\ldots,\alpha_m}
$$



#### We can define the **type generalization** function gen as follows:

 $\overline{\mathsf{gen} : (\mathbb{T} \times \mathbb{T} \times \Psi) \to \mathbb{T}^\forall}$  $gen(\tau, \Gamma, \psi) = \forall (\alpha_1, \ldots, \alpha_m) . \tau$  where  $free_\tau(\tau, \psi) \setminus free_\Gamma(\Gamma, \psi) = {\alpha_1, \ldots, \alpha_m}$ 

with the following definitions of **free type variables** in each component:

$$
\text{free}_{\tau}(\tau,\psi) = \left\{ \begin{array}{ll} \text{free}_{\tau}: (\mathbb{T}\times \Psi) \to \mathcal{P}(\mathbb{X}_{\alpha}) \\[1mm] \text{free}_{\tau}(\tau,\psi) & \text{if } \tau = \alpha \wedge \psi(\alpha) = \bullet \\[1mm] \text{free}_{\tau}(\tau',\psi) & \text{if } \tau = \alpha \wedge \psi(\alpha) = \tau' \\[1mm] \text{free}_{\tau}(\tau_p,\psi) \cup \text{free}_{\tau}(\tau_r,\psi) & \text{if } \tau = (\tau_p \to \tau_r) \\[1mm] \varnothing & \text{otherwise} \end{array} \right. \\[1mm] \text{free}_{\tau^{\vee}}: (\mathbb{T}^{\vee} \times \Psi) \to \mathcal{P}(\mathbb{X}_{\alpha}) \\[1mm] \text{free}_{\tau^{\vee}}(\forall (\alpha_1,\ldots,\alpha_m).\tau,\psi) = \text{free}_{\tau}(\tau,\psi) \setminus \{\alpha_1,\ldots,\alpha_m\} \\[1mm] \text{free}_{\Gamma}([x_1:\tau_1^{\vee},\ldots,x_n:\tau_n^{\vee}],\psi) = \text{free}_{\tau^{\vee}}(\tau_1^{\vee},\psi) \cup \ldots \cup \text{free}_{\tau^{\vee}}(\tau_n^{\vee},\psi)
$$



#### We can define the **type generalization** function gen as follows:

$$
\overline{\mathsf{gen} : (\mathbb{T} \times \mathbb{T} \times \Psi) \to \mathbb{T}^\forall}
$$

 $gen(\tau, \Gamma, \psi) = \forall (\alpha_1, \ldots, \alpha_m) . \tau$  where  $free_\tau(\tau, \psi) \setminus free_\Gamma(\Gamma, \psi) = {\alpha_1, \ldots, \alpha_m}$ 

Why do we need to subtract the free type variables  $\mathtt{free}_{\Gamma}(\Gamma,\psi)$  in the type environment Γ when generalizing the type *τ*?



#### We can define the **type generalization** function gen as follows:

$$
\overline{\mathsf{gen} : (\mathbb{T} \times \mathbb{T} \times \Psi) \to \mathbb{T}^\forall}
$$

 $g\text{en}(\tau, \Gamma, \psi) = \forall (\alpha_1, \dots, \alpha_m) . \tau$  where  $\text{free}_{\tau}(\tau, \psi) \setminus \text{free}_{\Gamma}(\Gamma, \psi) = {\alpha_1, \dots, \alpha_m}$ 

Why do we need to subtract the free type variables  $\mathbf{free}_{\Gamma}(\Gamma,\psi)$  in the type environment Γ when generalizing the type *τ*?

Consider the following example:

 $/*$  TIFAE  $*/$  $x \Rightarrow f$ // tyenv =  $[x: T1]$  and solution =  $[T1 -> ]$  (T1 is free in tyenv) **val z = x;**  $\frac{1}{2}$ : T1 (0) not z: [T1] { T1 } (X) **z**  $// z: T1 (0) not z: T2 (X)$ }

If we generalize the type T1 to [T1]  $\{$  T1 => T1  $\}$  for z, the types of x and z will be different even though they have exactly the same value.

#### <span id="page-48-0"></span>Recall: Example 3 – id





Let's define a new **type variable T2** to **instantiate** the **type variable T1**. And, **substitute** T1 with T2.

#### Recall: Example 3 – id





Let's define a new **type variable T3** to **instantiate** the **type variable T1**. And, **substitute** T1 with T3.

## Identifier Lookup with Type Instantiation

```
def typeCheck(e: Expr, tenv: TypeEnv, sol: Solution): (Type, Solution) = e match
  ...
  case Id(x) \Rightarrowval ty = tenv.getOrElse(x, error(s"free identifier: (x'))
    inst(ty, sol)
```

$$
\Gamma,\psi \vdash e:\tau,\psi
$$

$$
\tau-\text{Id}\; \frac{\Gamma(x)=\tau^\forall\; \; \frac{\texttt{inst}(\tau^\forall,\psi)=(\tau,\psi')}{\Gamma,\psi\vdash x:\tau,\psi'}
$$

We need to **instantiate** the type scheme *τ* <sup>∀</sup> with new type variables using the **type instantiation** function inst.

## Identifier Lookup with Type Instantiation

```
def typeCheck(e: Expr, tenv: TypeEnv, sol: Solution): (Type, Solution) = e match
  ...
  case Id(x) \Rightarrowval ty = tenv.getOrElse(x, error(s"free identifier: (x'))
    inst(ty, sol)
```

$$
\Gamma,\psi \vdash e:\tau,\psi
$$

$$
\tau-\text{Id}\; \frac{\Gamma(x)=\tau^\forall\; \; \frac{\texttt{inst}(\tau^\forall,\psi)=(\tau,\psi')}{\Gamma,\psi\vdash x:\tau,\psi'}
$$

We need to **instantiate** the type scheme *τ* <sup>∀</sup> with new type variables using the **type instantiation** function inst. For example,

$$
\mathtt{inst}(\forall \alpha. (\alpha \to \alpha), \varnothing) = (\beta \to \beta, [\beta \mapsto \bullet])
$$

### Type Instantiation



#### We can define the **type instantiation** function inst as follows:

$$
\boxed{\mathtt{inst} : (\mathbb{T}^\forall \times \Psi) \to (\mathbb{T} \times \Psi)}
$$

$$
\begin{array}{c}\n\text{inst}(\forall(\alpha_1,\ldots,\alpha_m).\tau,\psi) = (\text{subst}(\tau,\psi[\alpha_1\mapsto\alpha'_1,\ldots,\alpha_m\mapsto\alpha'_m]),\\ \psi[\alpha'_1\mapsto\bullet,\ldots,\alpha'_m\mapsto\bullet]\n\end{array}
$$

$$
\text{where} \qquad \alpha'_1,\ldots,\alpha'_m \notin \psi \land \forall 1 \leq i < j \leq m \ldotp \alpha'_i \neq \alpha'_j
$$

### Type Instantiation



#### We can define the **type instantiation** function inst as follows:

$$
\Big| \text{ inst} : (\mathbb{T}^\forall \times \Psi) \to (\mathbb{T} \times \Psi)
$$

$$
\begin{array}{c}\n\text{inst}(\forall(\alpha_1,\ldots,\alpha_m).\tau,\psi) = (\text{subst}(\tau,\psi[\alpha_1\mapsto\alpha_1',\ldots,\alpha_m\mapsto\alpha_m')), \\
\psi[\alpha_1'\mapsto\bullet,\ldots,\alpha_m'\mapsto\bullet]\n\end{array}
$$

$$
\text{where} \qquad \alpha'_1,\ldots,\alpha'_m \notin \psi \land \forall 1\leq i < j \leq m \ldotp \alpha'_i \neq \alpha'_j
$$

with the following **type substitution** function subst:

 $\texttt{subst} : (\mathbb{T} \times \Psi) \to \mathbb{T}$ 

$$
\texttt{subst}(\tau,\psi) = \left\{ \begin{array}{ll} \texttt{subst}(\tau',\psi) & \text{if } \tau = \alpha \wedge \psi(\alpha) = \tau' \\ \texttt{subst}(\tau_p,\psi) \rightarrow \texttt{subst}(\tau_r,\psi) & \text{if } \tau = (\tau_p \rightarrow \tau_r) \\ \tau & \text{otherwise} \end{array} \right.
$$

# Summary



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### Exercise  $#16$



<https://github.com/ku-plrg-classroom/docs/tree/main/cose212/tifae>

- Please see above document on GitHub:
	- Implement typeCheck function.
	- Implement interp function.
- It is just an exercise, and you **don't need to submit** anything.
- However, some exam questions might be related to this exercise.

## Final Exam



- **Date:** 18:30 21:00 (150 min.), December 18 (Wed.).
- **Location:** 205, Woojung Hall of Informatics (우정정보관)
- **Coverage:** Lectures 14 26
- **Format:** closed book and closed notes
	- Fill-in-the-blank questions about the PL concepts.
	- Write the evaluation results of given expressions.
	- Draw derivation trees of given expressions.
	- Define the syntax or semantics of extended language features.
	- Define typing rules for the given language features.
	- $e^{i\pi}$
- Note that there is **no class** on **December 16 (Mon.)**.

#### <span id="page-57-0"></span>Next Lecture



• Course Review

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