

Lecture 5 – ϵ -Nondeterministic Finite Automata (ϵ -NFA)

COSE215: Theory of Computation

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- ① Deterministic Finite Automata (DFA)
 - Definition
 - Transition Diagram and Transition Table
 - Extended Transition Function
 - Acceptance of a Word
 - Language of DFA (Regular Language)
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- ② Nondeterministic Finite Automata (NFA)
 - Definition
 - Transition Diagram and Transition Table
 - Extended Transition Function
 - Language of NFA
 - Examples
 - Equivalence of DFA and NFA
 - DFA \rightarrow NFA
 - DFA \leftarrow NFA (Subset Construction)

1. ϵ -Nondeterministic Finite Automata (ϵ -NFA)

- ϵ -Transition

- Definition

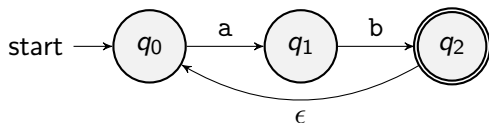
- Transition Diagram and Transition Table

- ϵ -Closures

- Extended Transition Function

- Language of ϵ -NFA

- Equivalence of DFA and ϵ -NFA



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Definition (ϵ -Nondeterministic Finite Automaton (ϵ -NFA))

An ϵ -nondeterministic finite automaton is a 5-tuple:

$$N_\epsilon = (Q, \Sigma, \delta, q_0, F)$$

- Q is a finite set of **states**
- Σ is a finite set of **symbols**
- $\delta : Q \times (\Sigma \cup \{\epsilon\}) \rightarrow \mathcal{P}(Q)$ is the **transition function**
- $q_0 \in Q$ is the **initial state**
- $F \subseteq Q$ is the set of **final states**

$$N_\epsilon = (\{q_0, q_1, q_2\}, \{a, b\}, \delta, q_0, \{q_2\})$$

$$\delta(q_0, a) = \{q_1\}$$

$$\delta(q_1, a) = \emptyset$$

$$\delta(q_2, a) = \emptyset$$

$$\delta(q_0, b) = \emptyset$$

$$\delta(q_1, b) = \{q_2\}$$

$$\delta(q_2, b) = \emptyset$$

$$\delta(q_0, \epsilon) = \emptyset$$

$$\delta(q_1, \epsilon) = \emptyset$$

$$\delta(q_2, \epsilon) = \{q_0\}$$

```
// The type definitions of states and symbols
type State = Int
type Symbol = Char
// The definition of epsilon-NFA
case class ENFA(
  states: Set[State],
  symbols: Set[Symbol],
  trans: Map[(State, Option[Symbol]), Set[State]],
  initState: State,
  finalStates: Set[State],
)
// An example of epsilon-NFA
val enfa: ENFA = ENFA(
  states = Set(0, 1, 2),
  symbols = Set('a', 'b'),
  trans = Map(
    (0, Some('a')) -> Set(1), (1, Some('a')) -> Set(), (2, Some('a')) -> Set(),
    (0, Some('b')) -> Set(), (1, Some('b')) -> Set(2), (2, Some('b')) -> Set(),
    (0, None)       -> Set(), (1, None)       -> Set(), (2, None)       -> Set(0),
  ),
  initState = 0,
  finalStates = Set(2),
)
```

$$N_\epsilon = (\{q_0, q_1, q_2\}, \{a, b\}, \delta, q_0, \{q_2\})$$

$$\delta(q_0, a) = \{q_1\}$$

$$\delta(q_1, a) = \emptyset$$

$$\delta(q_2, a) = \emptyset$$

$$\delta(q_0, b) = \emptyset$$

$$\delta(q_1, b) = \{q_2\}$$

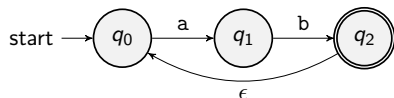
$$\delta(q_2, b) = \emptyset$$

$$\delta(q_0, \epsilon) = \emptyset$$

$$\delta(q_1, \epsilon) = \emptyset$$

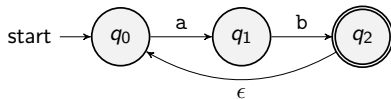
$$\delta(q_2, \epsilon) = \{q_0\}$$

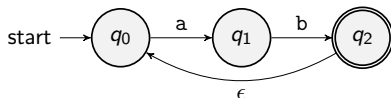
Transition Diagram



Transition Table

q	a	b	ϵ
$\rightarrow q_0$	$\{q_1\}$	\emptyset	\emptyset
q_1	\emptyset	$\{q_2\}$	\emptyset
$*q_2$	\emptyset	\emptyset	$\{q_0\}$





Definition (ϵ -Closures)

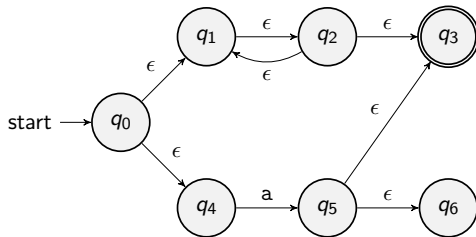
The ϵ -closure $\text{EClose}(q)$ for a state q is the set of all reachable states from q defined as follows:

- **(Basis Case)** $q \in \text{EClose}(q)$
- **(Induction Case)** $q' \in \text{EClose}(q) \wedge q'' \in \delta(q', \epsilon) \Rightarrow q'' \in \text{EClose}(q)$

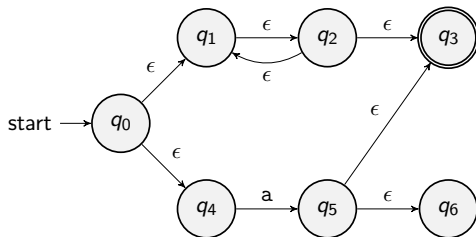
We sometimes need to define the ϵ -closure for a set of states S :

$$\text{EClose}(S) = \bigcup_{q \in S} \text{EClose}(q)$$

- $\text{EClose}(q_2) = \{q_0, q_2\}$

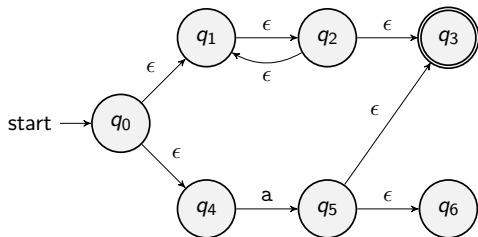


$EClose(q_0) =$



$$\text{EClose}(q_0) = \{q_0, q_1, q_2, q_3, q_4\}$$

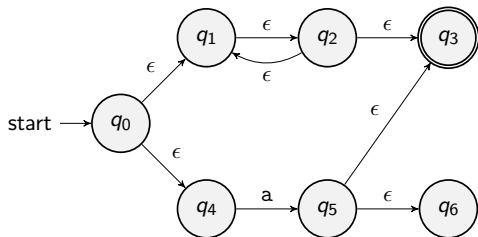
$$\text{EClose}(q_2) =$$



$$\text{EClose}(q_0) = \{q_0, q_1, q_2, q_3, q_4\}$$

$$\text{EClose}(q_2) = \{q_1, q_2, q_3\}$$

$$\text{EClose}(q_5) =$$

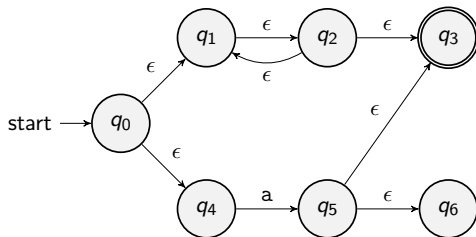


$$\text{EClose}(q_0) = \{q_0, q_1, q_2, q_3, q_4\}$$

$$\text{EClose}(q_2) = \{q_1, q_2, q_3\}$$

$$\text{EClose}(q_5) = \{q_3, q_5, q_6\}$$

$$\text{EClose}(\{q_2, q_5\}) =$$

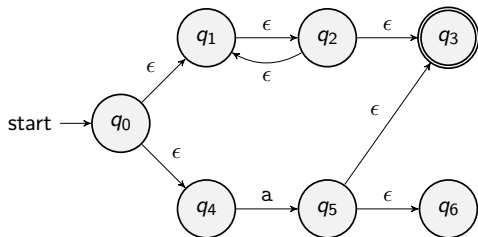


$$\text{EClose}(q_0) = \{q_0, q_1, q_2, q_3, q_4\}$$

$$\text{EClose}(q_2) = \{q_1, q_2, q_3\}$$

$$\text{EClose}(q_5) = \{q_3, q_5, q_6\}$$

$$\begin{aligned} \text{EClose}(\{q_2, q_5\}) &= \text{EClose}(q_2) \cup \text{EClose}(q_5) \\ &= \end{aligned}$$

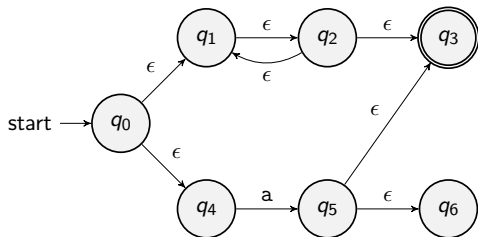


$$\text{EClose}(q_0) = \{q_0, q_1, q_2, q_3, q_4\}$$

$$\text{EClose}(q_2) = \{q_1, q_2, q_3\}$$

$$\text{EClose}(q_5) = \{q_3, q_5, q_6\}$$

$$\begin{aligned} \text{EClose}(\{q_2, q_5\}) &= \text{EClose}(q_2) \cup \text{EClose}(q_5) \\ &= \{q_1, q_2, q_3\} \cup \{q_3, q_5, q_6\} \\ &= \end{aligned}$$



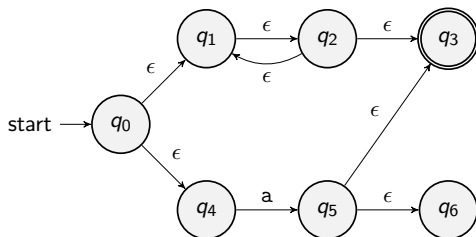
$$\text{EClose}(q_0) = \{q_0, q_1, q_2, q_3, q_4\}$$

$$\text{EClose}(q_2) = \{q_1, q_2, q_3\}$$

$$\text{EClose}(q_5) = \{q_3, q_5, q_6\}$$

$$\begin{aligned} \text{EClose}(\{q_2, q_5\}) &= \text{EClose}(q_2) \cup \text{EClose}(q_5) \\ &= \{q_1, q_2, q_3\} \cup \{q_3, q_5, q_6\} \\ &= \{q_1, q_2, q_3, q_5, q_6\} \end{aligned}$$

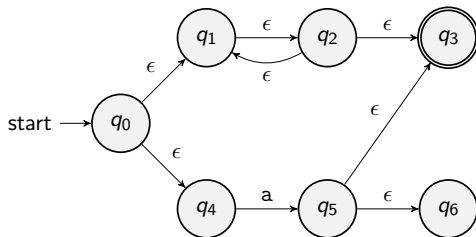

```
// Another example of epsilon-NFA
val enfa2: ENFA = ENFA(
  states = Set(0, 1, 2, 3, 4, 5, 6),
  symbols = Set('a'),
  trans = Map(
    (0, Some('a')) -> Set(), (0, None) -> Set(1, 4),
    (1, Some('a')) -> Set(), (1, None) -> Set(2),
    (2, Some('a')) -> Set(), (2, None) -> Set(1, 3),
    (3, Some('a')) -> Set(), (3, None) -> Set(),
    (4, Some('a')) -> Set(5), (4, None) -> Set(),
    (5, Some('a')) -> Set(), (5, None) -> Set(3, 6),
    (6, Some('a')) -> Set(), (6, None) -> Set(),
  ),
  initState = 0,
  finalStates = Set(3),
)
// The definitions of epsilon-closures
def eclose(enfa: ENFA)(q: State): Set[State] = ???
// The epsilon-closures for state 0, 2, and 5
eclose(enfa2)(0) // Set(0, 1, 2, 3, 4)
eclose(enfa2)(2) // Set(1, 2, 3)
eclose(enfa2)(5) // Set(3, 5, 6)
```



$$\text{EClose}(q_0) = \{q_0, q_1, q_2, q_3, q_4\}$$

```
// The WRONG definitions of epsilon-closures because of infinite loop
def wrongEClose(enfa: ENFA)(q: State): Set[State] =
  val basis = Set(q) // Basis Case
  val induc = enfa.trans(q, None) // Induction Case
  .flatMap(q => wrongEClose(enfa)(q))
  basis ++ induc

wrongEClose(enfa2)(5) // Set(3, 5, 6)
wrongEClose(enfa2)(2) // infinite loop
```



$$EClose(q_0) = \{q_0, q_1, q_2, q_3, q_4\}$$

```

// The definitions of epsilon-closures
def eclose(enfa: ENFA)(q: State): Set[State] =
  def aux(targets: List[State], visited: Set[State]): Set[State] = targets match
  case Nil => visited
  case p :: targets => aux(
    targets = (enfa.trans((p, None)) -- visited).toList ++ targets,
    visited = visited + p,
  )
  aux(List(q), Set())
  
```

Definition (Extended Transition Function)

For a given ϵ -NFA $N_\epsilon = (Q, \Sigma, \delta, q_0, F)$, the **extended transition function** $\delta^* : Q \times \Sigma^* \rightarrow \mathcal{P}(Q)$ is defined as follows:

- **(Basis Case)** $\delta^*(q, \epsilon) = \text{EClose}(q)$
- **(Induction Case)** $\delta^*(q, aw) = \bigcup_{q' \in \text{EClose}(q)} \bigcup_{q'' \in \delta(q', a)} \delta^*(q'', w)$

```
// The type definition of words
type Word = String
// A helper function to extract first symbol and rest of word
object `<|` { def unapply(w: Word) = w.headOption.map((_, w.drop(1))) }
// The extended transition function of epsilon-NFA
def extTrans(enfa: ENFA)(q: State, w: Word): Set[State] = w match
  case "" => eclose(enfa)(q)
  case a <| x => eclose(enfa)(q)
    .flatMap(q => enfa.trans(q, Some(a)))
    .flatMap(q => extTrans(enfa)(q, x))
```

Definition (Acceptance of a Word)

For a given ϵ -NFA $N_\epsilon = (Q, \Sigma, \delta, q_0, F)$, we say that N_ϵ **accepts** a word $w \in \Sigma^*$ if and only if $\delta^*(q_0, w) \cap F \neq \emptyset$

```
// The acceptance of a word by epsilon-NFA
def accept(enfa: ENFA)(w: Word): Boolean =
  val curStates: Set[State] = extTrans(enfa)(enfa.initState, w)
  curStates.intersect(enfa.finalStates).nonEmpty
```

Definition (Language of ϵ -NFA)

For a given ϵ -NFA $N_\epsilon = (Q, \Sigma, \delta, q_0, F)$, the **language** of N_ϵ is defined as follows:

$$L(N_\epsilon) = \{w \in \Sigma^* \mid N_\epsilon \text{ accepts } w\}$$

Theorem (Equivalence of DFA and ϵ -NFA)

A language L is the language $L(D)$ of a DFA D if and only if L is the language $L(N_\epsilon)$ of an ϵ -NFA N_ϵ .

Proof) By the following two theorems.

Theorem (DFA to ϵ -NFA)

For a given DFA $D = (Q, \Sigma, \delta, q, F)$, \exists ϵ -NFA N_ϵ . $L(D) = L(N_\epsilon)$.

Proof) Exercise (Refer to the previous lecture)

Theorem (ϵ -NFA to DFA – Subset Construction)

For a given ϵ -NFA $N_\epsilon = (Q, \Sigma, \delta, q_0, F)$, \exists DFA D . $L(D) = L(N_\epsilon)$.

Proof) Exercise (Refer to the previous lecture)

Theorem (ϵ -NFA to DFA – Subset Construction)

For a given ϵ -NFA $N_\epsilon = (Q, \Sigma, \delta_{N_\epsilon}, q_0, F)$, \exists DFA D . $L(D) = L(N_\epsilon)$.

Proof) Define a DFA

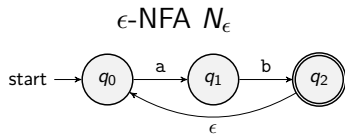
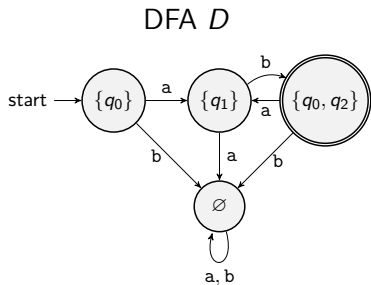
$$D = (Q_D, \Sigma, \delta_D, \text{EClose}(q_0), F_D)$$

where

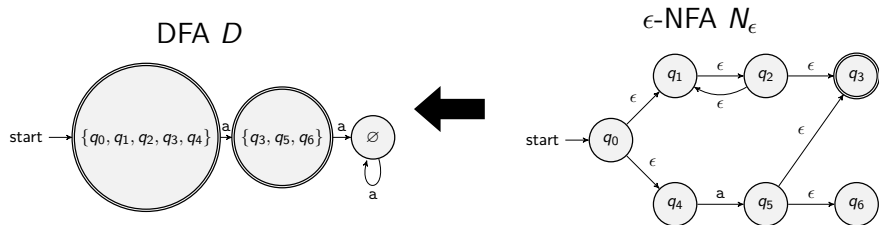
- $Q_D = \{S \subseteq Q \mid S = \text{EClose}(S)\}$
- $\forall S \in Q_D. \forall a \in \Sigma.$

$$\delta_D(S, a) = \text{EClose} \left(\bigcup_{q \in S} \delta_{N_\epsilon}(q, a) \right)$$

- $F_D = \{S \in Q_D \mid S \cap F \neq \emptyset\}$

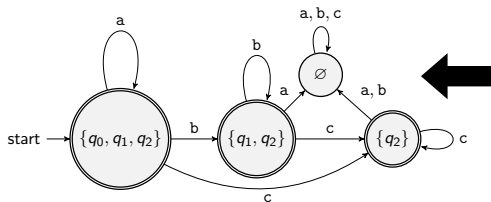


$$L(D) = L(N_\epsilon) = \{(ab)^n \mid n \geq 1\}$$

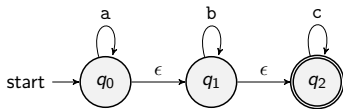


$$L(D) = L(N_\epsilon) = \{\epsilon, a\}$$

DFA D



ϵ -NFA N_ϵ



$$L(D) = L(N_\epsilon) = \{a^i b^j c^k \mid i, j, k \geq 0\}$$

1. ϵ -Nondeterministic Finite Automata (ϵ -NFA)

- ϵ -Transition

- Definition

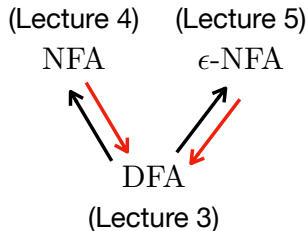
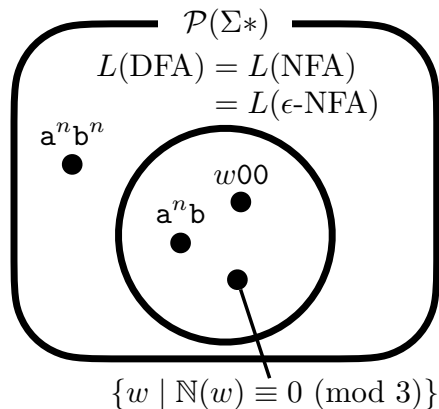
- Transition Diagram and Transition Table

- ϵ -Closures

- Extended Transition Function

- Language of ϵ -NFA

- Equivalence of DFA and ϵ -NFA



→ : Subset Construction

- Regular Expressions and Languages

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